Course Summary Linear Algebra with applications to differential equations College of the Atlantic. Winter 2019

Course Goals

- 1. I want you to learn what differential equations are and how to think about them: how they're used to model a range of phenomena and how to interpret their solutions.
- 2. I want you to gain a firm foundation in the basic concepts of elementary linear algebra, including: vectors, matrices, inverses, determinants, vector spaces, linear independence, sub-spaces, basic, dimension, rank, eigenvalues and eigenvectors.
- 3. I want you to gain an introduction to some of the basic analytic techniques used to analyze linear differential equations, including systems of linear equations.
- 4. I want you to gain mathematical confidence, appreciation, and "maturity". As part of this, I want you to continue to work toward developing a careful, systematic, and effective problem-solving style.
- 5. I want you to have fun and learn a lot.

Chronological List of Topics

- 1. Introduction to differential equations
- 2. Separable equations
- 3. Linear first-order equations; integrating factors
- 4. Introduction to linear systems
- 5. Matrices and row reduction
- 6. Matrix multiplication.
- 7. Matrix inverses
- 8. Determinants
- 9. Vector space and subspaces
- 10. Linear independence
- 11. Basis and dimension
- 12. Row and column spaces
- 13. Orthogonality and dot products
- 14. Eigenvectors and eigenvalues
- 15. Diagonalization and similarity
- 16. Second-order equations with constant coefficients
- 17. Systems of first-order differential equations
- 18. Relation between second-order equations and linear systems
- 19. Eigenvalue methods for solving linear systems of differential equations
- 20. Complex eigenvalues and eigenvectors
- 21. Deficient eigenvalues
- 22. Linearization and Jacobians

Facts about square matrices. The following statements about an $n \times n$ matrix A are equivalent:

- 1. A is nice¹.
- 2. A^{-1} exists.
- 3. Ax = 0 has only one solution: x = 0.
- 4. Ax = b has a unique solution.
- 5. The determinant of A is non-zero.
- 6. The columns of A are linearly independent.
- 7. The rows of A are linearly independent.
- 8. The column space of A is \mathbb{R}^n .
- 9. The row space of A is \mathbb{R}^n .
- 10. None of the eigenvalues equal zero.
- 11. A is non-singular.
- 12. The reduced row echelon form is the $n \times n$ identity matrix.
- 13. The rank of A is n.
- 14. The echelon form of A has n pivots.

A few elementary matrix properties. Let A, and B be matrices. Assume all products are defined.

1. $(A^{-1})^{-1} = A$

2.
$$(A^{\mathrm{T}})^{\mathrm{T}} = A$$

3.
$$(AB)^{-1} = B^{-1}A^{-1}$$

- 4. det(AB) = det(A) det(B)
- 5. $\det(A^{-1}) = 1/\det(A)$
- 6. It is not necessarily the case that $AB \neq BA$

 $^{^1\}mathrm{Not}$ a standard mathematical term

Linear algebra lets us study systems of equations as if they were just one equation. Suppose x, a, and b are **numbers**. Then

- 1. 1 is the multiplicative identity. 1a = a, for any a.
- 2. The inverse of a is $a^{-1} = \frac{1}{a}$. This means that $aa^{-1} = 1$.
- 3. The inverse exists unless a = 0.
- 4. Consider the equation ax = 0. The only solution to this equation is x = 0, unless a = 0, in which case there are infinitely many solutions.
- 5. If ax = 0 has a nonzero solution, then a is not invertible.
- 6. Consider the product ax. I can undo this and recover x by multiplying by the inverse: $a^{-1}ax = x$, unless a = 0.
- 7. The equation ax = b has a solution for any b, unless a = 0, in which case it has no solutions.

Let x and b be vectors, and A be a **matrix**.

- 1. I is the identity matrix. IA = A, for any A.
- 2. The inverse of A is A^{-1} . This means that $AA^{-1} = I$.
- 3. The inverse of A exists unless det A = 0.
- 4. Consider the equation Ax = 0. The only solution to this equation is x = 0, unless det A = 0.
- 5. If Ax = 0 has a nonzero solution, then A is not invertible.
- 6. Consider the product Ax. I can undo this and recover x by multiplying by the inverse: $A^{-1}Ax = x$, unless det A = 0.
- 7. The equation Ax = b has a solution for any b, unless det A = 0.